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# HYQUIP

### **QUICK-ACTING SWIN**

BASE, SPINDLE, AND LEVER: 1045 STEEL, HEAT TREATED, BLACK OXIDE FINISH CLAMPING-ARM BODY AND SPIRAL-CAM SHAFT: ALLOY STEEL, HEAT TREATED, BLACK OXIDE FINISH KNOB HANDLE: BLACK PHENOLIC PLASTIC



One-Touch Swing Clamps are manually operated clamps that first rotate 70° clockwise into position then clamp straight down in one continuous motion. The version shown here is operated by a radial cam lever that swings in an horizontal arc. Available in four sizes.

Starting with the clamping arm swung away for loading, turn the lever to rotate the arm into clamping position and automatically move the arm downward to apply clamping force. A small portion of the total vertical stroke is used to swing, and slightly advance the clamping arm, then the remaining stroke is available as the clamping range. To unclamp, reverse the lever movement to lift the arm straight up and automatically return the arm to its original position for loading.

Mount clamp with two socket-head cap screws using the two mounting slots. To allow for workpiece variation, adjust spindle extension so that full clamping force is achieved approximately in the middle of the lever's 100° clamping range.









1. Starting position, with clamping 2. Turn lever (70°) to rotate the 3. Continue turning lever (through 90°) to 4. Continue turning lever (90° to 190°) advance the arm toward the workpiece. until full clamping force is applied.

HORIZONTAL CAM LEVER (INCH)

	MAX	MAX.	SWING			Α																		Т		
	CLAMPING	ALLOWABLE	AND	CLAMPING	UN-	STARTOF	END OF	e																SOCKET		
	FORCE	TORQUE	ADVANCE	STROKE	CLAMPED	CLAMPING	CLAMPING			D										P				SET-	U	V
PART NO.	(LBS)	(FT-LBS)	STROKE	(MAX.)	POSITION	RANGE	RANGE	B	C	DIA	E	F	G	н	J	K	L	Μ	N	DIA	Q	R	S	SCREW	DIA	DIA
CL-100-QSCR	250	4	.03	.04	1.21	1.18	1.14	.39	.71	.71	1.80	1.93	1.02	.87	.24	.45	.31	.169	1.97	.59	1.42	.24	.88	#8-32	.169	1.063
CL-150-QSCR	400	7	.04	.06	1.62	1.58	1.52	.55	.91	.91	2.41	2.60	1.38	1.18	.31	.60	.39	.209	2.48	.79	1.77	.31	1.00	#10-24	.209	1.339
CL-200-QSCR	500	12	.05	.06	2.02	1.97	1.91	.71	1.18	1.18	3.01	3.23	1.77	1.46	.31	.81	.63	.331	3.15	1.02	2.56	.47	1.50	5/16-18	.331	1.890
CL-300-QSCR	800	23	.07	.07	2.43	2.36	2.29	.87	1.57	1.57	3.66	3.94	2.17	1.77	.31	1.00	.79	.409	3.94	1.30	3.35	.59	2.00	3/8-16	.409	2.520
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8/19 | Carr Lane Manufacturing Co. | 285

### Advance 臣 Stroke



# HYQUIP

#### ONE-TOUCH QUICK-ACTING SWING CLAMPS

BASE, WASHER, AND SPINDLE: 1045 STEEL, HEAT TREATED, BLACK OXIDE FINISH CLAMPING-ARM BODY AND CAM HANDLE: ALLOY STEEL, HEAT TREATED, BLACK OXIDE FINISH



#### **VERTICAL CAM HANDLE (INCH)**

	MAX	MAX.	SWING		A																		Т	Ú.	
	CLAMPING	ALLOWABLE	AND	CLAMPING	UN-	START OF	END OF																SOCKET		
	FORCE	TORQUE	ADVANCE	STROKE	CLAMPED	CLAMPING	CLAMPING			D													SET-	U	V
PART NO.	(LBS)	(FF-LBS)	STROKE	(MAX.)	POSITION	RANGE	RANGE	В	С	DIA	F	G	н	J	K	L	Μ	Ν	Ρ	Q	R	S	SCREW	DIA	DIA
CL-100-QSCV	180	4	.03	.04	1.21	1.18	1.14	.39	.71	.71	2.05	1.02	.87	.24	.45	.31	.169	1.97	.63	1.42	.24	.88	#8-32	.169	1.063
CL-150-QSCV	340	7	.04	.06	1.62	1.58	1.52	.55	.91	.91	2.68	1.38	1.18	.31	.60	.39	.209	2.48	.75	1.77	.31	1.00	#10-24	.209	1.339
CL-200-QSCV	470	12	.05	.06	2.02	1.97	1.91	.71	1.18	1.18	3.43	1.77	1.46	.31	.81	.63	.331	3.15	.94	2.56	.47	1.50	5/16-18	.331	1.890
CL-300-QSCV	630	22	.07	.07	2.43	2.36	2.29	.87	1.57	1.57	4.21	2.17	1.77	.31	1.00	.79	.409	3.94	1.8	3.35	.59	2.00	3/8-16	.409	2.520

286 | Carr Lane Manufacturing Co. | 8/19

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#### ONE-TOUCH QUICK-ACTING SWING CLAMPS

BASE, WASHER, SPINDLE, AND HEX DRIVE NUT: 1045 STEEL, HEAT TREATED, BLACK OXIDE FINISH CLAMPING-ARM BODY: ALLOY STEEL, HEAT TREATED, BLACK OXIDE FINISH



Hex Drive

One-Touch Swing Clamps are manually operated clamps that first rotate 70° clockwise into position then clamp straight down in one continuous motion. The version shown here is operated by a screw mechanism with a hex drive nut. This allows for exact clamping-force control using a torque wrench. The screw mechanism also provides a longer clamping stroke and greater clamping force than the versions with cam locking. Available in four sizes.

Starting with the clamping arm swung away for loading, tighten the hex drive nut to rotate the arm into clamping position and automatically move the arm downward to apply clamping force. A small portion of the total vertical stroke is used to swing the clamping arm, then the remaining stroke is available as the clamping range. To unclamp, turn the flange nut counterclockwise to lift the arm straight up and automatically return the arm to its original position for loading.

Mount clamp with two socket-head cap screws using the two mounting slots. To allow for workpiece variation, adjust spindle extension so that full clamping force is achieved approximately in the middle of the lever's 100° clamping range.

	HEX DRIVE (INCH)																									
1		MAX	MAX.	SWING			A																	T		
		CLAMPING	ALLOWABLE	AND	CLAMPING	UN-	START OF	END OF																SOCKET		
		FORCE	TORQUE	ADVANCE	STROKE	CLAMPED	CLAMPING	CLAMPING			D													SET-	U	V
	PART NO.	(LBS)	(FF-LBS)	STROKE	(MAX.)	POSITION	RANGE	RANGE	B	C	DIA	F	G	H	J	K	L	M	N	P	Q	R	S	SCREW	DIA	DIA
	CL-100-QSCH	500	4.5	.02	.12	1.16	1.14	1.02	.39	.71	.71	2.22	1.02	.87	.24	.45	.31	.169	1/4-20	7/16	1.42	.24	.88	#8-32	.169	1.063
	CL-150-QSCH	800	8	.02	.16	1.56	1.54	1.38	.55	.91	.91	2.89	1.38	1.18	.31	.60	.39	.209	5/16-18	1/2	1.77	.31	1.00	#10-24	.209	1.339
	CL-200-QSCH	1300	21	.03	.16	1.92	1.89	1.73	.71	1.18	1.18	3.58	1.77	1.46	.31	.81	.63	.331	3/8-16	9/16	2.56	.47	1.50	5/16-18	.331	1.890
	CL-300-QSCH	1700	33	.03	.20	2.31	2.28	2.08	.87	1.57	1.57	4.49	2.17	1.77	.31	1.00	.79	.409	1/2-13	3/4	3.35	.59	2.00	3/8-16	.409	2.520
	CL-200-QSCH CL-300-QSCH	1300	33	.03	.16	2.31	2.28	2.08	./1 .87	1.18	1.18	4.49	2.17	1.46	.31	.81 1.00	.63 .79	.331 .409	3/8-16 1/2-13	9/16 3/4	2.56 3.35	.4/ .59	2.00	3/8-16	.331 .409	1

8/19 | Carr Lane Manufacturing Co. | 287



Starting with the clamping arm swung away for loading, tighten the flange nut to rotate the arm into clamping position and automatically move the arm downward to apply clamping force.

